

For Immediate Release  
November 19, 2015



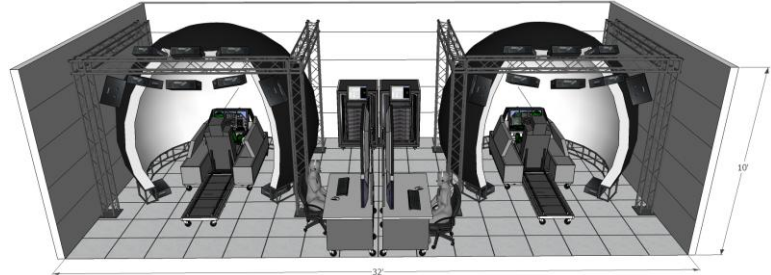
## ZedaSoft, Inc. awarded support contract for Integrated Collision Avoidance System (ICAS) program by Lockheed Martin's Skunk Works

(Fort Worth, Texas – November 19, 2015) Fort Worth-based ZedaSoft®, Inc. has been awarded a contract by Lockheed Martin to support the Integrated Collision Avoidance System (ICAS). This follow-on program is a continuation of the Automatic Air Collision Avoidance System (Auto ACAS) and Automatic Ground Collision Avoidance System (Auto GCAS) developed by Lockheed Martin's Skunk Works.

Both the Auto ACAS and the Aviation Week Laureate Award-winning Auto GCAS programs were developed in conjunction with the U.S. Air Force Research Laboratory (AFRL) at Wright Patterson AFB, Ohio. The ICAS phase will test the integration of these two automatic collision avoidance technologies on USAF F-16 fighter aircraft.

ZedaSoft is excited to support these integrated collision avoidance technologies. Recently fielded on USAF F-16s, Auto GCAS has already been credited with saving pilots & aircraft in both the training and operational environments. The system is expected to be offered as an upgrade for other military aircraft in the future. The following link is to an excellent article by Aviation Week detailing ICAS: <http://aviationweek.com/technology/testing-combined-air-ground-anti-collision-system>

ZedaSoft delivered a dual-dome solution with two F-16C Reconfigurable Cockpit Systems (RCS) and two Reconfigurable Desktop Systems (RDS) used as ground stations, to support development and testing of these life-saving technologies.



“We believe that this integrated dual-dome solution developed by ZedaSoft provides the best test platform and value to this very important technology development program.” said GW Estep, president of ZedaSoft.

For additional information contact:  
ZedaSoft, Inc.  
Deborah Hall  
817-616-1000 x224  
[debbie.hall@zedasoft.com](mailto:debbie.hall@zedasoft.com)  
[www.zedasoft.com](http://www.zedasoft.com)